### Equations over finite algebras

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# I. Systems of term equations

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# Systems of term equations

Let  $\mathbf{A}$  be an algebra. TERMSYSSAT $(\mathbf{A})$  is the following problem:

#### Given:

Terms  $s_1(x_1, ..., x_n), t_1(x_1, ..., x_n), ..., s_k(x_1, ..., x_n), t_k(x_1, ..., x_n).$ 

#### Asked:

Is there  $\boldsymbol{a} \in A^n$  with  $s_1^{\boldsymbol{A}}(\boldsymbol{a}) = t_1^{\boldsymbol{A}}(\boldsymbol{a}), \ldots, s_k^{\boldsymbol{A}}(\boldsymbol{a}) = t_k^{\boldsymbol{A}}(\boldsymbol{a})$ ?

#### Remarks:

- ▶ The answer is always **yes** if **A** has a one-element subuniverse: groups, lattices.
- Allowing constants yields  $POLSYSSAT(\mathbf{A})$ , which can be harder.

# Computational complexity of $\text{TERMSYSSAT}(\mathbf{A})$

One can solve the equations by solving a constraint satisfaction problem. **Idea:** (Larose, Zádori 2006) Instead of solving

$$f(g(x_1, x_2)) = f(x_1),$$

solve

$$(x_1, x_2, y_1) \in g^{\circ}, (y_1, y_2) \in f^{\circ}, (x_1, y_2) \in f^{\circ}, \text{ where}$$
  
 $g^{\circ} = \{(a_1, a_2, b) \in A^3 \mid g(a_1, a_2) = b\}$ 

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is the graph of g. This reduces TERMSYSSAT(A; f, g) to  $CSP(A; f^{\circ}, g^{\circ})$ .

## Computational complexity of $\text{TERMSYSSAT}(\mathbf{A})$

For an algebra  $\mathbf{A} = (A; F)$ , let  $\mathbf{A}^{\circ} := (A; \{f^{\circ} \mid f \in F\})$ .

As a consequence of the Bulatov-Zhuk-Dichotomy (2017) (in the form of Barto, Krokhin, Willard (2017)), one obtains:

#### Theorem (cf. [Mayr, MFCS 2023]).

(Assume  $\mathbf{P} \neq \mathbf{NP}$ ). Let  $\mathbf{A}$  be a finite algebra. Then TERMSYSSAT $(\mathbf{A}) \in \mathbf{P} \iff \mathbf{A}^{\circ}$  has a (not necessarily idempotent) Taylor polymorphism. Otherwise TERMSYSSAT $(\mathbf{A})$  is **NP**-complete.

# Computational complexity of $\text{TERMSYSSAT}(\mathbf{A})$

**Question:** Algebraic description when  $\mathbf{A}^{\circ}$  has a (not necessarily idempotent) Taylor polymorphism.

**Definition.** Let **A** be a finite algebra.

 $Core(\mathbf{A})$  is a minimal endomorphic image of  $\mathbf{A}$  w.r.t  $\subseteq$ . (Defined up to isomorphism)

### Examples.

• **G** group. 
$$Core(\mathbf{G}) = \{1\}.$$

▶ **G** group.  $\mathbf{G}^* := (G; *, {}^{-1}, (c_g)_{g \in G}))$  its expansions with all constants from G. Then Core( $\mathbf{G}^*$ ) = G.

$$Core((S_5; \circ, {}^{-1}, \underbrace{\operatorname{id}, (1 \ 2)}_{\operatorname{nullary}})) = \{\operatorname{id}, (1 \ 2)\}.$$

# Computational complexity of TERMSYSSAT(A)

#### Theorem Larose, Zádori 2006

Let **A** be a finite algebra in a congruence modular variety. TFAE:

- 1. PolSysSat( $\mathbf{A}$ ) = TermSysSat( $\mathbf{A}^*$ )  $\in \mathbf{P}$ .
- 2. A is abelian.

#### **Theorem** Mayr 2023

Let **A** be a finite algebra in a congruence modular variety. TFAE:

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- 1. TermSysSat( $\mathbf{A}$ )  $\in \mathbf{P}$ .
- 2.  $Core(\mathbf{A})$  is abelian.

Both results also hold also if  $1 \notin \operatorname{typ}(V(\mathbf{A}))$  and  $5 \notin \operatorname{typ}(\{\mathbf{A}\})$ .

# TERMSYSSAT(A) vs. POLSYSSAT(A)

#### Theorem Mayr 2023.

Let  $\mathbf{A}$  be a finite algebra of finite type. The following three problems are reducible to each other in constant time:

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- 1. TermSysSat( $\mathbf{A}$ ).
- 2. TermSysSat( $Core(\mathbf{A})$ ).
- 3.  $PolSysSat(Core(\mathbf{A}))$ .

# The meta-problem for systems of term equations

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### The meta-problem for TERMSYSSAT

**Meta-problem** for TERMSYSSAT (Assume  $\mathbf{P} \neq \mathbf{NP}$ )

Given:  $\mathbf{A} = (A; f_1, \dots, f_k)$ Asked: Is TERMSYSSAT $(\mathbf{A}) \in \mathbf{P}$ ?

## The meta-problem for TERMSYSSAT

**Meta-problem** for TERMSYSSAT (Assume  $\mathbf{P} \neq \mathbf{NP}$ )

**Given:**  $A = (A; f_1, ..., f_k)$ 

Asked: Is TERMSYSSAT $(\mathbf{A}) \in \mathbf{P}$ ?

Asked: Does  $Core(\mathbf{A}^{\circ})$  have a Siggers polymorphism?

## The meta-problem for TERMSYSSAT

**Meta-problem** for TERMSYSSAT (Assume  $\mathbf{P} \neq \mathbf{NP}$ )

**Given:**  $A = (A; f_1, ..., f_k)$ 

Asked: Is TERMSYSSAT $(\mathbf{A}) \in \mathbf{P}$ ?

**Asked:** Does  $Core(\mathbf{A}^{\circ})$  have a Siggers polymorphism?

In cm varieties: Asked: Does A have an abelian core?

#### Theorem Mayr 2023

There is a quasi-polynomial algorithm that decides whether a given finite  $\mathbf{A}$  in a cm variety has an abelian core.

q(n) is quasi-polynomial if  $\exists c, d, N > 0 \ \forall n \ge N : q(n) \le c2^{\log(n)^d}$ .

# Solving CSPs by solving term equations

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# Solving CSP's through systems of equations

#### Theorem.

For every finite relational structure  $\mathbb{D}$  of finite type, there is a finite algebra  $\mathbf{A}(\mathbb{D})$  such that  $\mathrm{CSP}(\mathbb{D})$  and  $\mathrm{TERMSYSSAT}(\mathbf{A}(\mathbb{D}))$  are polynomial time reducible to each other.

1. Klíma, Tesson, Thérien 2007:

Assume  $\mathbb{D} = (D, \rho)$  is a digraph.  $\mathbf{A}(\mathbb{D})$  is a semigroup with  $5|D| + |\rho| + 1$  elements that satisfies  $x^2 \approx x$  and  $xyz \approx yxz$ .

2. Broniek 2015:

Assume  $\mathbb{D} = (D, R)$  with  $R \subseteq D^r$ .  $\mathbf{A}(\mathbb{D})$  is a unary algebra with |D| + |R| + 2 elements and r + 4 unary operations.

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Let  $\mathbf{A}$  be an  $\mathbf{R}$ -module.

► The polynomial algorithm provided by the theory uses the Bulatov-Dalmau-algorithm (2006) to solve instances of CSP(A°), which has the Mal'cev term of A as a polymorphism.

▶ In practice, Hermite-decomposition is useful.

We solve

$$\left(\begin{array}{rrr} 10 & 16 & 0\\ 15 & 24 & 30 \end{array}\right) \cdot \begin{pmatrix} x\\ y\\ z \end{pmatrix} = \left(\begin{array}{r} 4\\ 66 \end{array}\right)$$

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over  $\mathbb{Z}$ .

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over  $\mathbb Z.$  To this end, we compute a  $\mathbb Z\text{-}\mathsf{Basis}$  of the row module of

$$\left(\begin{array}{rrrrr} -4 & -66 & 1 & 0 & 0 & 0 \\ 10 & 15 & 0 & 1 & 0 & 0 \\ 16 & 24 & 0 & 0 & 1 & 0 \\ 0 & 30 & 0 & 0 & 0 & 1 \end{array}\right)$$

using the Hermite normal form (1851, polynomial time since 1979).

We solve

$$\left(\begin{array}{rrr} 10 & 16 & 0\\ 15 & 24 & 30 \end{array}\right) \cdot \left(\begin{array}{c} x\\ y\\ z \end{array}\right) = \left(\begin{array}{c} 4\\ 66 \end{array}\right)$$

over  $\mathbb{Z}$ . We have

$$\operatorname{row}\left(\begin{pmatrix} -4 & -66 & 1 & 0 & 0 & 0\\ 10 & 15 & 0 & 1 & 0 & 0\\ 16 & 24 & 0 & 0 & 1 & 0\\ 0 & 30 & 0 & 0 & 0 & 1 \end{pmatrix}\right) = \operatorname{row}\left(\begin{pmatrix} 2 & 3 & 0 & 5 & -3 & 0\\ 0 & 30 & 0 & 0 & 0 & 1\\ 0 & 0 & 1 & 2 & -1 & 2\\ 0 & 0 & 0 & 8 & -5 & 0 \end{pmatrix}\right)$$

and thus  $S = \{(2, -1, 2) + t (8, -5, 0) \mid t \in \mathbb{Z}\}.$ 

**Problem:** Find all  $(z_1, z_2, z_3) \in \mathbb{Z}[x, y]^3$  with

$$(10y)z_1 + 0z_2 + (4x)z_3 = 4x^3.$$

**Solution:** Compute the (reduced strong) Gröbner basis (with respect to a certain order) of the row module of

$$A' := \begin{pmatrix} -4x^3 & 1 & 0 & 0 & 0\\ 10y & 0 & 1 & 0 & 0\\ 0 & 0 & 0 & 1 & 0\\ 4x & 0 & 0 & 0 & 1 \end{pmatrix}.$$

We solve  $(10y)z_1 + 0z_2 + (4x)z_3 = 4x^3$ .

$$\operatorname{row}\left(\begin{pmatrix} -4x^{3} & 1 & 0 & 0 & 0\\ 10y & 0 & 1 & 0 & 0\\ 0 & 0 & 0 & 1 & 0\\ 4x & 0 & 0 & 0 & 1 \end{pmatrix}\right) = \operatorname{row}\left(\begin{pmatrix} 2xy & 0 & x & 0 & -2y\\ 4x & 0 & 0 & 0 & 1\\ 10y & 0 & 1 & 0 & 0\\ 0 & 1 & 0 & 0 & x^{2}\\ 0 & 0 & 2x & 0 & -5y\\ 0 & 0 & 0 & 1 & 0 \end{pmatrix}\right).$$

Hence  $S = (0, 0, x^2) + \langle (2x, 0, -5y), (0, 1, 0) \rangle$ .

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# II. One equation

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## Supernilpotent algebras

#### Theorem (Coordinatization, EA 2019).

Let **A** be supernilpotent of order  $p^{\alpha}$  in a cm variety. Then there are operations  $+, \times$  on A and  $D \in \mathbb{N}$  such that

- 1.  $\mathbb{F} = (A; +, \times)$  is a field,
- 2. for all  $n \in \mathbb{N}$  and  $p \in \operatorname{Pol}_n(\mathbf{A})$ , there is by  $P \in \mathbb{F}[X_1, \ldots, X_n]$  with  $P^{\mathbb{F}} = p^{\mathbf{A}}$ and  $\operatorname{deg}(f) \leq D$ .

#### Corollary Kompatscher 2018.

Let  $\mathbf{A}$  be supernilpotent in a cm variety. Then one equation

$$s(x_1,\ldots,x_n)=t(x_1,\ldots,x_n)$$

can be solved in polynomial time.

## Supernilpotent algebras

#### Corollary Kompatscher 2018.

Let **A** be supernilpotent in a cm variety. Then one equation  $s(x_1, \ldots, x_n) = t(x_1, \ldots, x_n)$  can be solved in polynomial time.

• Assume 
$$|A| = p^{\alpha} =: q$$

▶  $\exists S, T \in \mathbb{F}_q[X_1, \dots, X_n] : S^{\mathbb{F}} = s^A$  and  $T^{\mathbb{F}} = t^A$  with deg $(S) \leq D$ , deg $(T) \leq D$ .

• 
$$\deg(1 - (S - T)^{q-1}) \le (q - 1)D.$$

▶ Let  $(a_1, \ldots, a_n)$  be the nonzero of  $P := 1 - (S - T)^{q-1}$  with the smallest number of nonzero entries. WLOG  $(a_1, \ldots, a_n) = (a_1, \ldots, a_k, 0, \ldots, 0)$ .

► 
$$Q(X_1, \ldots, X_k) := P(X_1, \ldots, X_k, 0, \ldots, 0)$$
 satisfies deg $(Q) \ge k$ .

► Hence  $k \leq (q-1)D$ .

Look for a solution of s = t with at most (q-1)D entries different from  $a \in A$ .

# Supernilpotent algebras

Why was it easy to solve equations?

- We could reduce the search space from  $|A|^n$  to a hitting set of size  $c(|A|) n^k$ .
- ▶ There are either no or many solutions.

### Theorem Warning 1935.

 $f \in \mathbb{F}_q[X_1,\ldots,X_n].$ 

If the polynomial f with  $\deg(f) < n$  has a zero, then the number of zeros of f is at least  $q^{n-\deg(f)}$ .

**Consequence:** if there is a solution, picking a at random yields a solution with probability at least  $q^{-\deg(f)} \rightsquigarrow$  linear time Monte Carlo-algorithm (Kawałek, Krzackowski 2020).

# Solving equations over groups

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## Solving equations over groups

 ${\bf G}$  a finite group.  ${\sf POLSAT}({\bf G})$  asks whether

$$s(x_1,\ldots,x_k,g_1,\ldots,g_l)=t(x_1,\ldots,x_k,g_1,\ldots,g_l)$$

has a solution in  $G^k$ .

Input size: lengths of terms s and t.

- ▶ **G** nilpotent  $\Rightarrow$  POLSAT(**G**)  $\in$  **P** (Horváth, 2011).
- ▶ **G** not solvable  $\Rightarrow$  POLSAT(**G**) is **NP**-complete (Goldmann and Russell, 1999).
- ▶ **G** not solvable  $\Rightarrow$  there exists  $e \in \text{Pol}_1(\mathbf{A})$  such that  $\text{POLSAT}(\mathbf{A} + e)$  has no subexponential algorithm, or the exponential time hypothesis fails (Rossi, EA 2024).
- ▶  $\mathbf{G} = P \rtimes A$  with P p-group and A abelian  $\Rightarrow$  POLSAT $(\mathbf{G}) \in \mathbf{P}$ . (Földvári, Horváth 2019).

Even solving a fixed number of equations is in  $\mathbf{P}$  (Nuspl 2021).

## **Theorem** Idziak, Kawałek, Krzaczkowski; Weiß 2020 If $\text{PoLSAT}(S_4) \in \mathbf{P}$ , then for every $\varepsilon > 0$ , we can solve 3-SAT in time $O(2^{\varepsilon n})$ , contradicting the Exponential Time Hypothesis by Impagliazzo and Paturi from 1999.

- The result is not just about  $S_4$ , but about all groups of Fitting length (length of shortest composition series with nilpotent quotients) at least 3.
- An algorithm with running time  $O(n^{c(\log(n))^d})$  is consistent with ETH, where n is the length of the input terms.

# Solving equations over groups

• We make a (still unsuccessful) attempt to find an  $O(n^{c(\log(n))^d})$  algorithm for POLSAT $(S_4)$ .

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► Easier problem: POLEQV( $S_4$ ): Input: p, q polynomial terms over  $S_4$ . Output: Is  $\forall a \in S_4^n : p(a) = q(a)$  true?

## Identity checking for groups

We want to check whether  $p(x_1, \ldots, x_n) = 1$  for all  $\boldsymbol{x} \in S_4^n$ .

**Definition.**  $p \in \text{Pol}_k(S_4)$  is absorbing if for all  $\boldsymbol{x}: 1 \in \{x_1, \ldots, x_k\} \Rightarrow p(x_1, \ldots, x_k) = 1.$ 

- Suppose we can prove: every nonconstant absorbing polynomial has length at least  $2^{ck^{1/d}}$ .
- ▶ Then pick  $\boldsymbol{a}$  with  $p(\boldsymbol{a}) \neq 1$  with maximal amount of 1's. WLOG  $\boldsymbol{a} = (a_1, \ldots, a_k, 1, \ldots, 1).$
- ▶ Then  $q(x_1, \ldots, x_k) := p(x_1, \ldots, x_k, 1, \ldots, 1)$  is absorbing.
- Hence length $(p) \ge 2^{ck^{1/d}}$ .
- ▶ Then  $k \leq \frac{1}{c} (\log_2(\text{length}(p)))^d$ .
- Input size m: greater than  $\max(n, \operatorname{length}(p))$ .
- ► There are at most  $m^{c_2 \log^d(m)}$  tuples with at most k entries  $\neq 1 \rightsquigarrow$  algorithm of complexity  $O(m^{c \log^d(m)})$ .

# Finite fields

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# Absorbing polynomial functions over finite fields

**Definition.** Let  $\mathbb{F}$  be a field,  $f \in \mathbb{F}[X_1, \ldots, X_n]$  is absorbing at a for  $S : \Leftrightarrow \forall (x_1, \ldots, x_n) \in S^n : a \in \{x_1, \ldots, x_n\} \Rightarrow f(x_1, \ldots, x_n) = 0.$ 

Theorem (Grünbacher, Hametner, EA 2024).

 $S \subseteq \mathbb{F}_q \setminus \{0\}, a \in S$ . If  $f \in \mathbb{F}_q[X_1, \ldots, X_n]$  is absorbing at a for S and f is not identically 0 on S, then f contains at least  $(\frac{q-1}{q-2})^n$  monomials.

#### Examples:

- 1.  $\omega := \text{primitive element of } \mathbb{F}_4,$   $S := \{1, \omega\}.$  Then  $f := \prod_{i=1}^n (X_i - \omega)$  is absorbing at  $\omega$  for S and has  $2^n$ monomials.
- 2. (Grünbacher) There is an absorbing function with at most  $(\sqrt[q-2]{q-1})^n$  monomials (if  $q-2 \mid n$ ).



### Equation solving over finite fields

Intuition: If there is a solution, there is one in the neighborhood.

Theorem Grünbacher, Hametner, EA 2024

Let  $q > 2, n \in \mathbb{N}, f \in \mathbb{F}_q[X_1, \dots, X_n] \setminus \{0\}$  with M(f) monomials,  $S \subseteq \mathbb{F}_q \setminus \{0\},$  $t := \frac{q-1}{q-2}$ . Let  $V(f) := \{ \boldsymbol{x} \in S^n \mid f(\boldsymbol{x}) = 0 \}.$ 

If  $V(f) \neq \emptyset$ , then for every  $\boldsymbol{a} \in S^n$ , there is  $\boldsymbol{b} \in V(f)$  with

$$d_H(\boldsymbol{a}, \boldsymbol{b}) \le \frac{1}{\log_2(t)} (1 + (q-1)\log_2(M(f))).$$

This gives quasi-polynomial time algorithms for the following questions:

- 1. Does f have a zero in  $S^n$ ?
- 2. Does f vanish identically on  $S^n$ ?

# III. Quasi-identities

### Quasi-identities in universal algebra

▶ A algebra,  $s_i, t_i, u, v$  terms.

- We ask whether  $S = \{ \boldsymbol{x} \in A^n \mid \bigwedge_{i \in \underline{k}} s_i(\boldsymbol{x}) = t_i(\boldsymbol{x}) \}$  is contained in  $U = \{ \boldsymbol{x} \in A^n \mid u(\boldsymbol{x}) = v(\boldsymbol{x}) \}.$
- ▶ This holds if the formula

$$\forall \boldsymbol{x} : \left( \bigwedge_{i \in \underline{k}} s_i(\boldsymbol{x}) = t_i(\boldsymbol{x}) \right) \Longrightarrow u(\boldsymbol{x}) = v(\boldsymbol{x})$$

holds in  $\mathbf{A}$ .

- ▶ Such a formula is called a conditional identity or quasi-identity.
- We want to determine the validity of this formula.

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### Algebras that satisfy the same quasi-identities

Some facts on quasi-identities:

- ► Classes of algebras defined by quasi-identities are called quasivarieties. The quasivariety generated by K is  $ISP_{u}P_{fin}K$ .
- Generalization: infinite pre-condition, finitely many variables:
   Considered in Universal Algebraic Geometry. Closure operator: LSP.
- Generalization: infinite pre-condition, arbitrary many variables: Closure operator *ISP*.

▶ **A**, **B** finite, of finite type,  $|\mathbf{A}| = n$ . Then  $\mathbf{A} \in Q(\mathbf{B}) \Leftrightarrow \mathbf{A} \in IS\{\mathbf{B}^{\binom{n}{2}}\}$ .

### Quasi-identity validity

Let  $\mathbf{A}$  be an algebra. QUASIIDVAL $(\mathbf{A})$  is the problem:

**Given:** A quasi-identity  $\Phi := \forall \boldsymbol{x} : \left( \bigwedge_{i \in \underline{k}} s_i(\boldsymbol{x}) = t_i(\boldsymbol{x}) \right) \Longrightarrow u(\boldsymbol{x}) = v(\boldsymbol{x}).$ Here,  $s_i, t_i, u, v$  are terms in the language of  $\mathbf{A}$  over the variables  $\boldsymbol{x}$ .

Asked: Does  $\Phi$  hold in A?

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**Asked:** Does  $\Phi$  hold in **A**?

Computational Complexity: For finite  $\mathbf{A}$  of finite type, QUASIIDVAL( $\mathbf{A}$ ) is in co-NP:

 $a \in A^n$  witnesses failure of  $\Phi$  if  $\left( \bigwedge_{i \in \underline{k}} s_i^{\mathbf{A}}(a) = t_i^{\mathbf{A}}(a) \right) \wedge u^{\mathbf{A}}(a) \neq v^{\mathbf{A}}(a)$ .

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**Exponential time method:** A quasi-identity of length  $\ell$  contains at most  $\ell$  different variables that can take at most  $|A|^{\ell}$  values.

Question: For which algebras do we have faster methods (e.g. polynomial time)?

## Quasi-identity validity and polynomial systems

### Relations to other problems:

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- ▶ If we can decide solvability of polynomial systems, then we can check the validity of quasi-identities.
- ▶ We search for a counter-example:  $\forall \boldsymbol{x} : \left( \bigwedge_{i \in \underline{k}} s_i(\boldsymbol{x}) = t_i(\boldsymbol{x}) \right) \Longrightarrow u(\boldsymbol{x}) = v(\boldsymbol{x})$ holds iff for all  $a, b \in A$  with  $a \neq b$ ,

$$\bigwedge_{i \in \underline{k}} s_i(\boldsymbol{x}) = t_i(\boldsymbol{x}), \ u(\boldsymbol{x}) = a, \ v(\boldsymbol{x}) = b$$

has no solution.

These systems use constants: a and b.
Therefore they are polynomial systems and not just term systems.

## Quasi-identity validity and polynomial systems

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$$\bigwedge_{i \in \underline{k}} s_i(\boldsymbol{x}) = t_i(\boldsymbol{x}), \ u(\boldsymbol{x}) = a, \ v(\boldsymbol{x}) = b$$

has no solution.

- These systems use constants: a and b.
  Therefore they are polynomial systems and not just term systems.
- ► Conclusion:  $QUASIIDVAL(\mathbf{A}) \leq_{truth table} POLSYSSAT(\mathbf{A}).$

Quasi-identity validity and systems of term equations

▶ If we can check the validity of quasi-identities, then we can decide solvability of term equations.

### Quasi-identity validity and systems of term equations

- ▶ If we can check the validity of quasi-identities, then we can decide solvability of term equations.
- The system  $s_1 = t_1, \ldots, s_k = t_k$  has no solution iff

$$s_1 = t_1 \land \ldots \land s_k = t_k \Longrightarrow y = z$$

is valid in **A**.  $(y, z \dots$  new variables, |A| > 1).

### Quasi-identity validity and systems of term equations

- ▶ If we can check the validity of quasi-identities, then we can decide solvability of term equations.
- The system  $s_1 = t_1, \ldots, s_k = t_k$  has no solution iff

$$s_1 = t_1 \land \ldots \land s_k = t_k \Longrightarrow y = z$$

is valid in **A**.  $(y, z \dots$  new variables, |A| > 1).

▶ Conclusion: co-TERMSYSSAT( $\mathbf{A}$ )  $\leq_P$  QUASIIDVAL( $\mathbf{A}$ ).

Quasi-identity validity and checking term equivalence

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### **Connections:**

- $\blacktriangleright \text{ QUASIIdVAL}(\mathbf{A}) \leq_{\text{truth table POLSYSSAT}}(\mathbf{A}).$
- ► co-TERMSYSSAT( $\mathbf{A}$ )  $\leq_P$  QUASIIDVAL( $\mathbf{A}$ ).
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- ► TERMEQV( $\mathbf{A}$ )  $\leq_P$  QUASIIDVAL( $\mathbf{A}$ ).
- ▶ In 2004, M. Volkov constructed a 10-element semigroup Q with TERMEQV(Q) ∈ P, and QUASIIDVAL(Q) co-NP-complete because it solves 3-COLORABILITY for graphs.

# Let **A** be an algebra with a Mal'cev term. **Consequences:**

▶ A is abelian  $\implies$  QUASIIDVAL(A)  $\in$  P. (Reason: POLSYSSAT, which is analyzed in [Larose, Zádori 2006])

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**Open:** nonabelian nilpotent groups, nonzero nilpotent rings.

## A reduction of graph coloring to quasi-identities

### Theorem Aichinger, Grünbacher, STACS 2023

 ${\bf A}$  finite algebra of finite type with a Mal'cev term. Then

- 1. QUASIIDVAL $(\mathbf{A}) \in \mathbf{P}$  if  $\mathbf{A}$  is abelian.
- 2.  $QUASIIDVAL(\mathbf{A})$  is co-**NP**-complete if  $\mathbf{A}$  is nonabelian.

New content: item (2).

**Proof idea:** we reduce the *H*-coloring problem to  $QUASIIDVAL(\mathbf{A})$ .

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## H-coloring of graphs

*H*-COLORING: **Given:** a graph *G*. **Asked:** Is there a graph homomorphism *h* from *G* to *H* ( $G \rightarrow H$ )?

 $\blacktriangleright H = K_2:$ 



 $G \to H$  iff G is bipartite: edges in G only go from  $h^{-1}(\{1\})$  to  $h^{-1}(\{2\})$ .

H-coloring of graphs

*H*-COLORING: **Given:** a graph *G*. **Asked:** Is there a graph homomorphism *h* from *G* to *H* ( $G \rightarrow H$ )?

 $\blacktriangleright$   $H = K_4$ :



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 $G \to H$  if the vertices of G can be coloured with 4 colors such that no adjacent vertices have the same colour.

H-coloring of graphs

*H*-COLORING: **Given:** a graph *G*. **Asked:** Is there a graph homomorphism *h* from *G* to *H* ( $G \rightarrow H$ )?

 $\blacktriangleright$  *H* a graph with loops:



 $G \to H$  holds for every graph G: use h(v) = 3 for each vertex v of G.

### Theorem Hell, Nešetřil 1990.

Let H be a finite loopless graph that contains a triangle. Then H-COLORING is **NP**-complete.

A consequence stated in CSP-language:

#### Theorem

Let  $\mathbb{H} = (H, \rho)$  be a relational structure with an antireflexive and symmetric binary relation  $\rho$ .

If  $\mathbb{H}$  has  $\mathbb{K}_3 = (\{1, 2, 3\}; \neq)$  as a substructure, then  $Csp(\mathbb{H})$  is **NP**-complete.

### Proof of the Theorem

### Plan:

- ► We want to prove that checking the validity of quasi-identities of R := (3Z<sub>27</sub>, +, -, ·, 0) is co-NP-complete.
- We will show: there is a graph H such that

for every graph  $G: G \to H \iff$  the quasi-identity  $\Phi(G)$  is not valid.

▶ This will imply that  $QUASIIDVAL(\mathbf{R})$  is co-**NP**-complete.

#### Details:

- $R = \{ [0]_{27}, [3]_{27}, \dots, [24]_{27} \}.$
- ► *H* is the "difference graph" or "apartness graph" on *R* : (*r*, *s*) is an edge if  $r - s \notin \{[0]_{27}, [9]_{27}, [18]_{27}\}$ .

$$E(H) = \{ (x, y) \mid x - y \notin \{0, 9, 18\} \}.$$

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## Proof of the Theorem

$$E(H) = \{ (x, y) \mid x - y \notin \{0, 9, 18\} \}.$$

 $\blacktriangleright$  non-edges of H

## Proof of the Theorem

The graph H for  $3\mathbb{Z}_{27}$ 



• G graph. We want to find out whether  $G \rightarrow H$  using a quasi-identity on **R**.

• 
$$\Phi = \left(\bigwedge_{(u,v)\in E(G)} a = z_{u,v} \cdot (x_u - x_v)\right) \Rightarrow a = 0.$$

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- Suppose  $\Phi$  is invalid. Then  $a \neq 0$ .
- ▶ Let  $(u, v) \in E(G)$ . Then  $x_u x_v \notin \{0, 9, 18\}$ .
- ▶ Thus  $(x_u, x_v)$  is an edge of H.
- $u \mapsto x_u$  is a homomorphism from G to H.

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• Hence if  $\Phi$  is invalid,  $G \to H$ .

### Proof of the Theorem

The graph H for  $3\mathbb{Z}_{27}$ 



G graph. We want to find out whether G → H using a quasi-identity on R.
Φ = ( ∧ a = z<sub>u,v</sub> ⋅ (x<sub>u</sub> - x<sub>v</sub>)) ⇒ a = 0.

▶ Suppose  $G \to H$ .

 $(u,v) \in E(G)$ 

• . . .

- ▶ This is a counterexample to  $\Phi$ .
- Hence  $\Phi$  is invalid.

### Proof of the Theorem

- Hence  $\Phi$  is not valid iff  $G \to H$ .
- ▶ *H*-coloring is **NP**-complete [Hell, Nešetřil 1990].

▶ Thus  $QUASIIDVAL(\mathbf{R})$  is co-**NP**-complete.

### Proof for Mal'cev algebras

#### Theorem

Let  $\mathbf{A}$  be a finite nonabelian algebra of finite type with a Mal'cev term. Then QUASIIDVAL( $\mathbf{A}$ ) is co-**NP**-complete.

- Instead of the ring multiplication, use commutators [Smith 1976, Hagemann, Herrmann 1979].
- ▶ This works for subdirectly irreducible **A**.
- ▶ For arbitrary **A**, use "difference graphs" for several congruences of **A**.
- Order these graphs and pick a maximal one.
- ▶ EA and Simon Grünbacher. The Complexity of Checking Quasi-Identities over Finite Algebras with a Mal'cev Term, STACS 2023.

## IV. Open questions

### Polynomial equations on $S_4$

**Problem:** Solve  $POLSAT(S_4)$  or  $POLEQV(S_4)$  in time  $m^{c \log^d(m)}$ .

Possible approaches:

- Show: every nonconstant absorbing polynomial in k arguments has length at least  $2^{ck^{1/d}}$ .
- ▶ The following problems are in some sense equivalent:
  - ▶ Does a fully expanded polynomial  $p \in Mat_2(\mathbb{F}_2) \langle X_1, \ldots, X_n \rangle$  vanish on all  $6^n$  invertible inputs?
  - (Grünbacher) Let  $\omega$  be primitive in  $\mathbb{F}_4$ ,  $p_1, \ldots, p_n$  expanded polynomials in  $\mathbb{Z}_3[X_1, \ldots, X_n]$ . Does

$$\sum_{i=1}^{n} \omega^{p_i(X_1,\dots,X_n)}$$

vanish on  $\{-1, 1\}^n$ ?

## Circuit equivalence

- The polynomials p, q may be given as circuits.
- ▶ We want to test whether they compute the same function.

Problem 1 from [Kawałek, Kompatscher, Krzaczkowski, STACS 2024] Let **A** be a finite algebra from a congruence modular variety with supernilpotent rank 2. Is there a deterministic polynomial time algorithm solving circuit equivalence on **A**?

Děkuji za pozvání a pozornost!